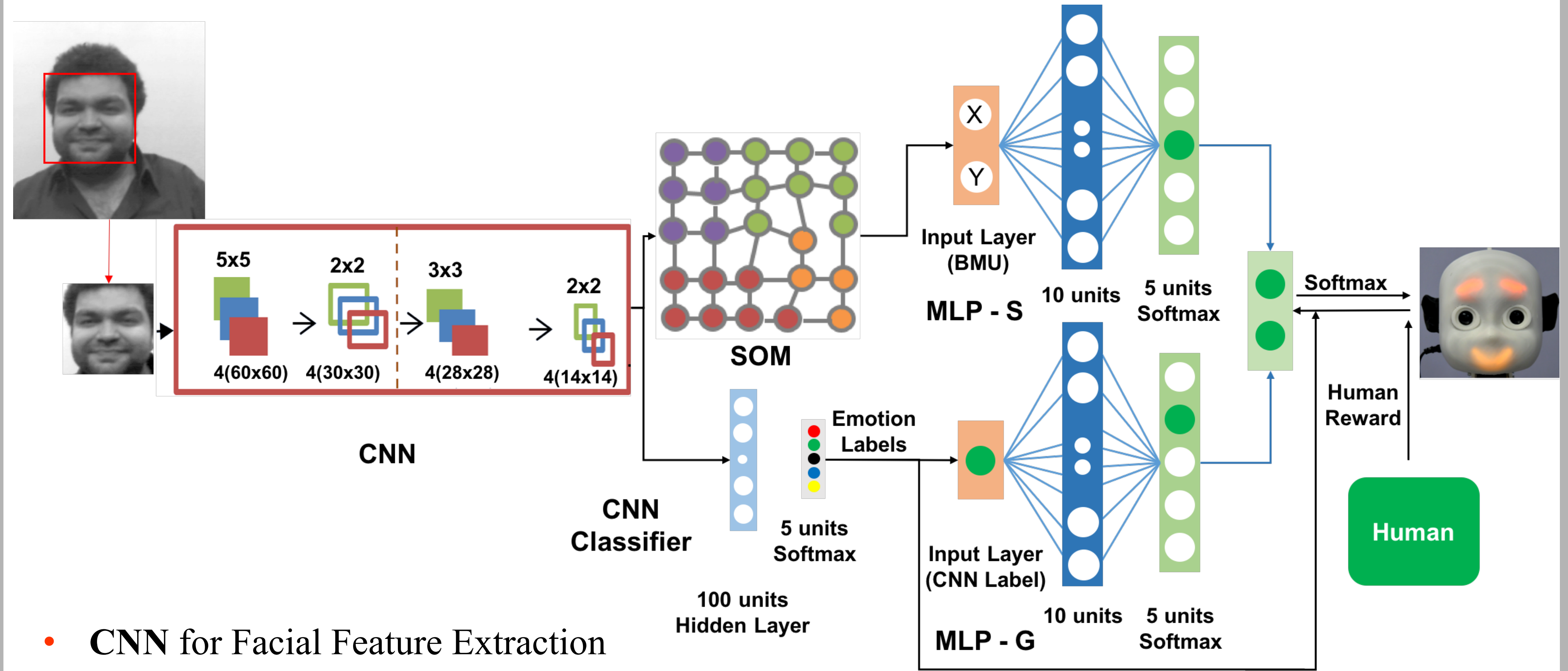


Motivation

- For better decision making and a pleasant user experience, agents need to be **more sociable**.
- It is important for agents to not only recognise emotions but also to **express emotions** in a way which is apprehensible for humans.
- The motivation behind this study is to explore the possibility of **training agents** to express emotions.
- People express and perceive emotions differently and thus, the agents need to **adapt** to this variance.
- Neuro-Inspired Companion (NICO) Robot for neuro-cognitive research.



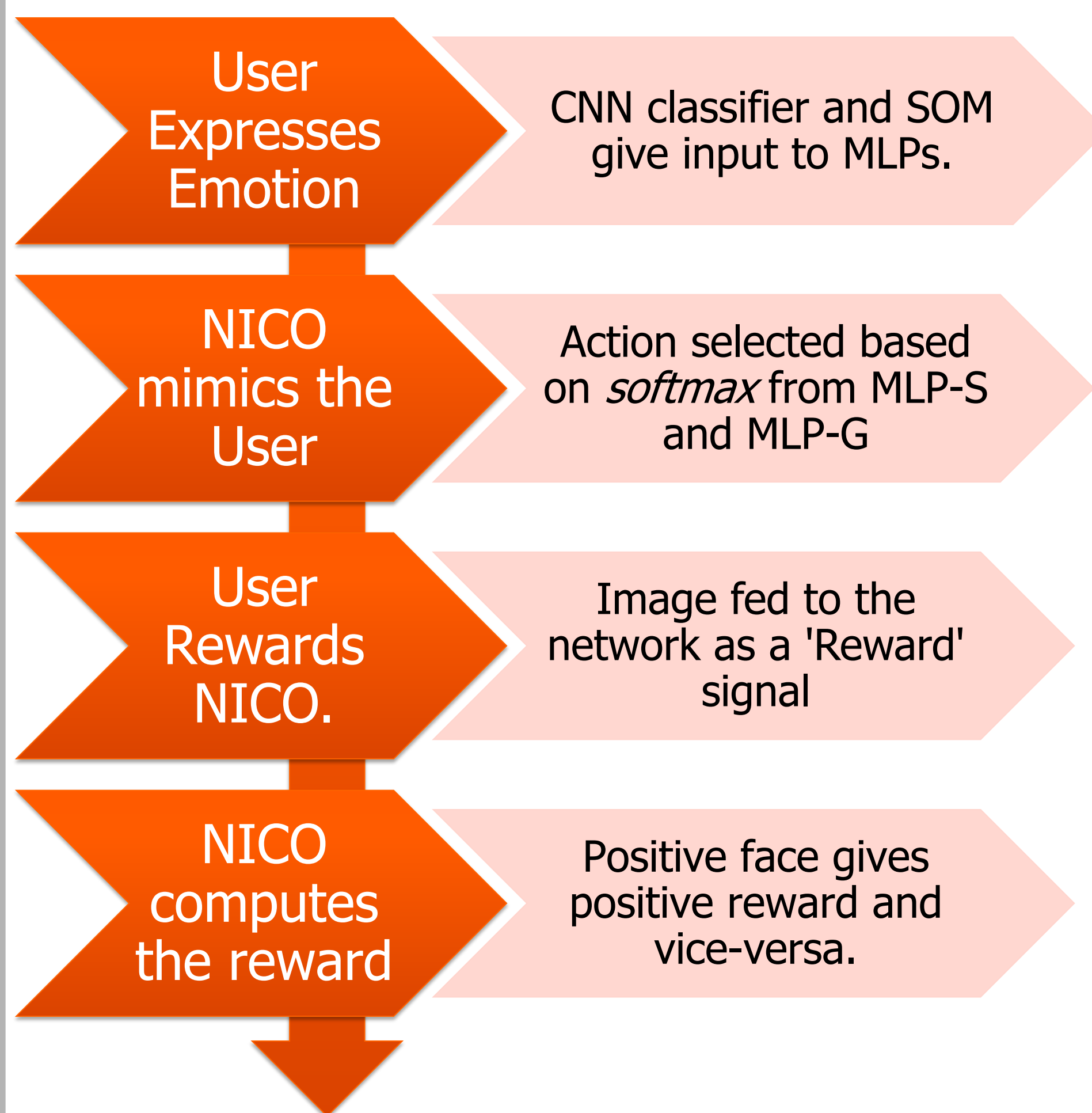
Approach



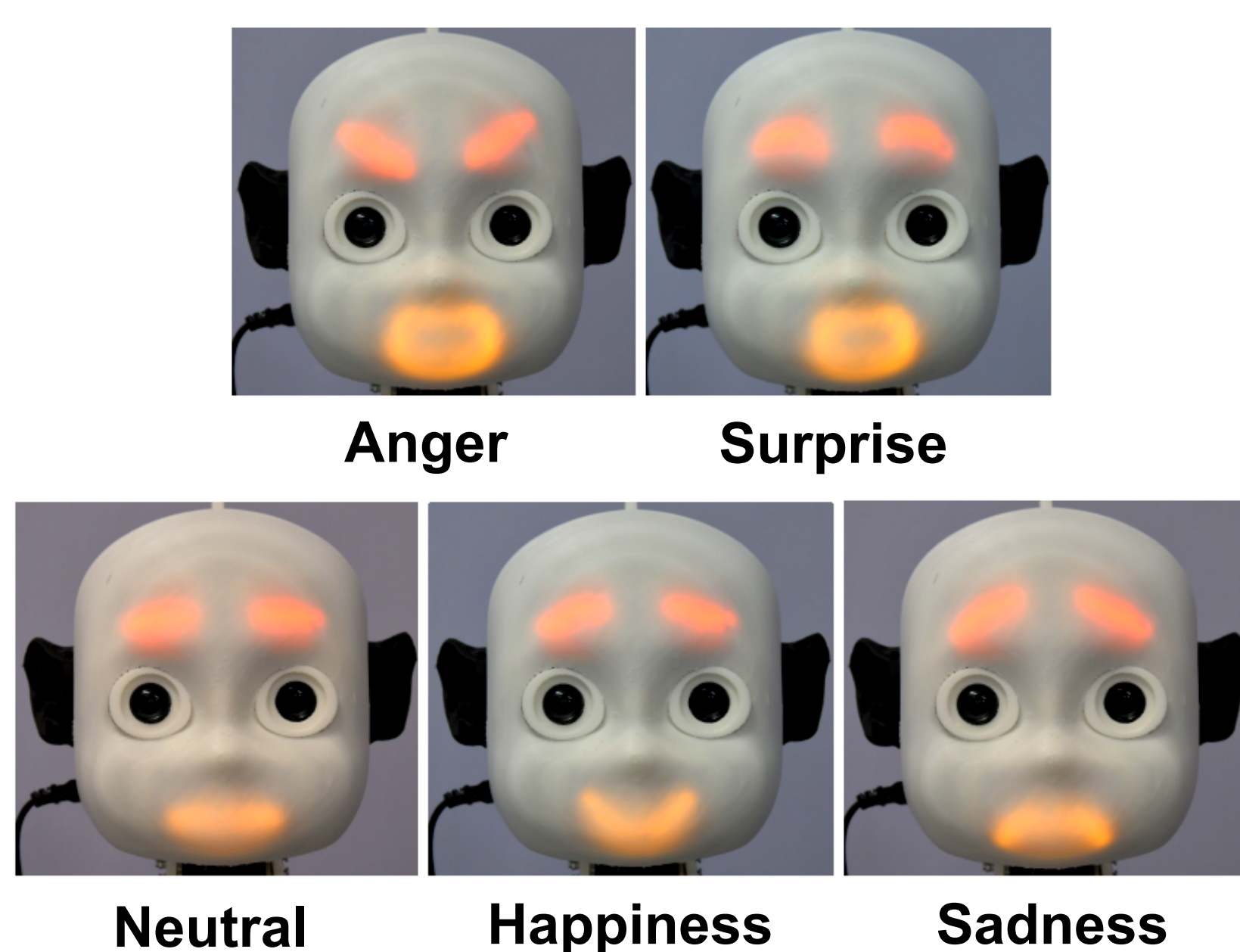
- CNN** for Facial Feature Extraction
- Feature representations are then used to train the **SOM**. The classifier from the **CNN** is used in parallel to classify emotional input to provide ground-truth.
- Multilayer Perceptron consists of two branches, namely, **MLP-Generic** and **MLP-Specific**.

Scenario

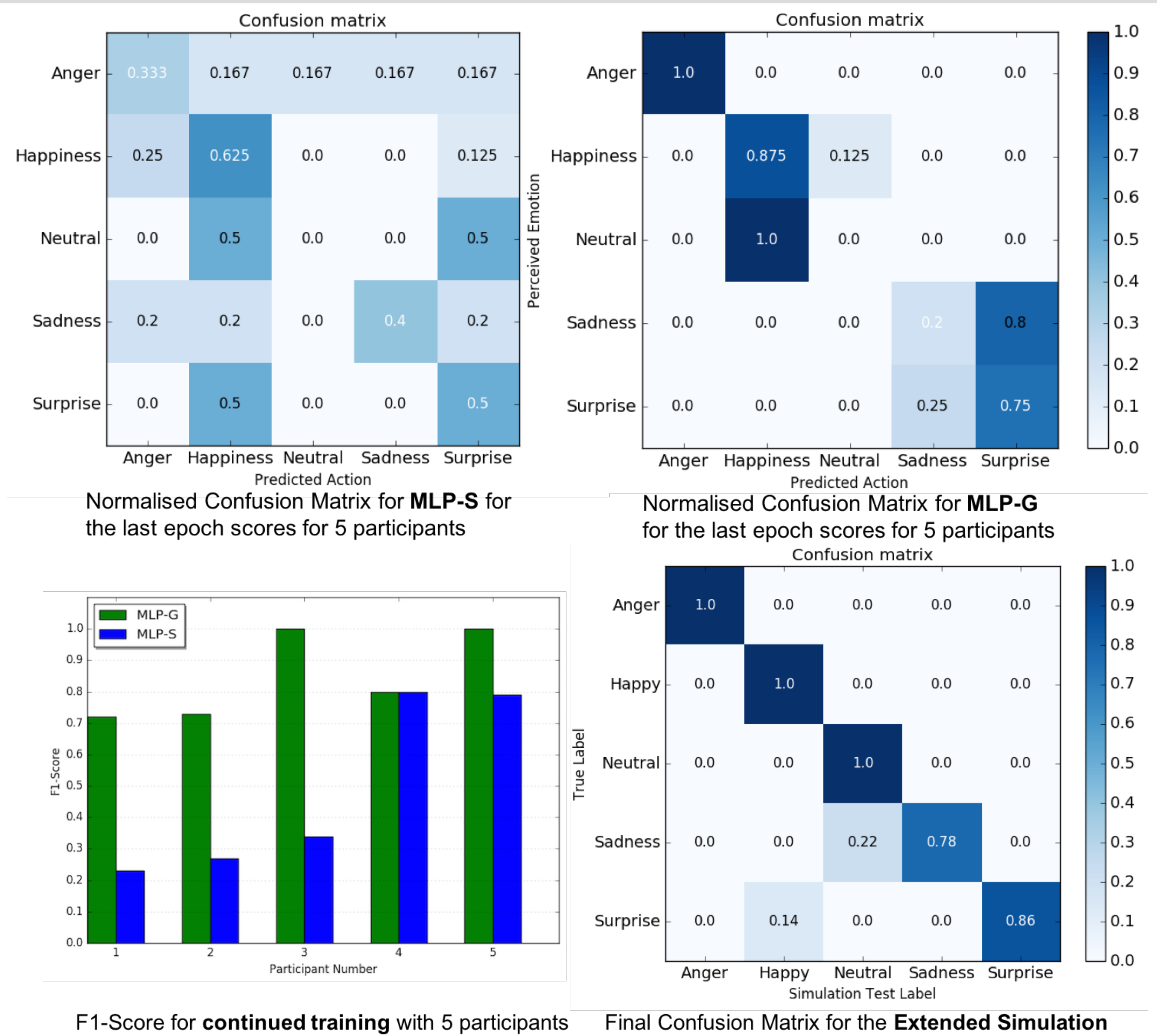
- The CNN is **pre-trained** using the Cohn-Kanade+ dataset and data collected during the experiments.
- For each experiment, the SOM is trained and **customised** to the user's face and expressions.
- Each interaction between the agent and the user can be split into **four** steps:



NICO expression representations used in the study can be seen in the figure below:



Results



Conclusion

- Two branches of the model take inspiration from the generic and specific perception of emotions in humans.
- MLP-G** acts on the generic, "first impression" model of the network whereas the **MLP-S** learns to adapt to a particular individual.
- Continued training improves performance. **MLP-G** provides initial guidance but eventually **MLP-S** outperforms **MLP-G** adapting to each individual.

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