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MIDDLE EAST TECHNICAL UNIVERSITY

AULA-Caps: Lifecycle-Aware Capsule Networks for Spatio-Temporal Analysis of Facial Actions





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Engineering and
Physical Sciences
Research Council

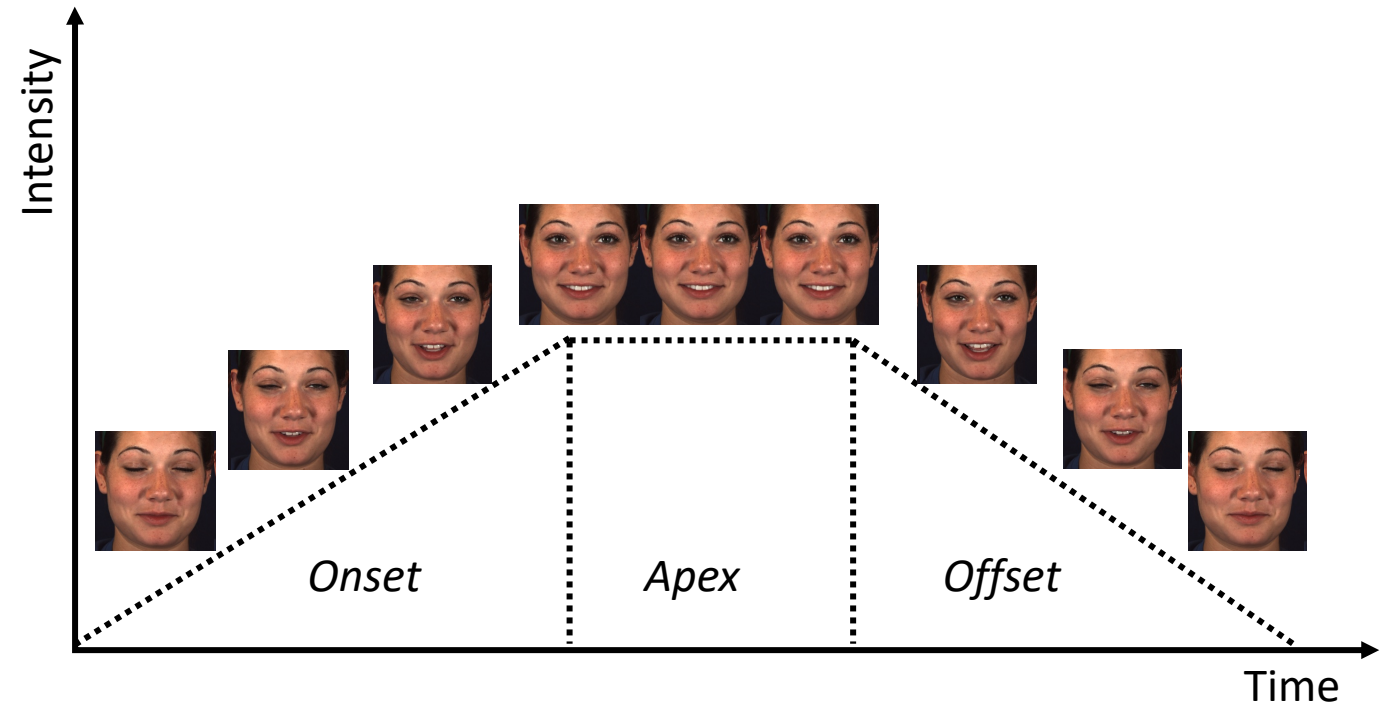
Motivation: Facial Action Coding System

- Facial Action Coding System (FACS) (Ekman *et al.* 1978) provides **objective** evaluations of Human Facial Expressions.
- Facial **AUs** encode muscle activity.
- **Precise representation** of facial activity.
- **No subjective interpretation** needed.

Upper Face Action Units					
AU 1	AU 2	AU 4	AU 5	AU 6	AU 7
 Inner Brow Raiser *AU 41	 Outer Brow Raiser *AU 42	 Brow Lowerer *AU 43	 Upper Lid Raiser AU 44	 Cheek Raiser AU 45	 Lid Tightener AU 46
 Lid Droop	 Slit	 Eyes Closed	 Squint	 Blink	 Wink
Lower Face Action Units					
AU 9	AU 10	AU 11	AU 12	AU 13	AU 14
 Nose Wrinkler AU 15	 Upper Lip Raiser AU 16	 Nasolabial Deepener AU 17	 Lip Corner Puller AU 18	 Cheek Puffer AU 20	 Dimpler AU 22
 Lip Corner Depressor AU 23	 Lower Lip Depressor AU 24	 Chin Raiser *AU 25	 Lip Puckerer *AU 26	 Lip Stretcher *AU 27	 Lip Funneler AU 28
 Lip Tightener	 Lip Pressor	 Lips Part	 Jaw Drop	 Mouth Stretch	 Lip Suck

Motivation: The AU Lifecycle

- Facial Action Unit (AU) Activation follows a temporal evolution: the **AU Lifecycle**.
- Facial muscles contract to form the **onset** phase.
- Complete contraction at the **apex** state.
- Muscles start to relax in the **offset** phase.



Motivation: Spatial vs. Spatio-temporal Features

Spatial Features

- Capture **local relationships** between facial regions.
- **Hierarchical features** sensitive to **local variations**.
- Contiguous frames in the **apex** phase experience **low** variations.
- Spatial features provide more **descriptive** information during the **apex** phase.

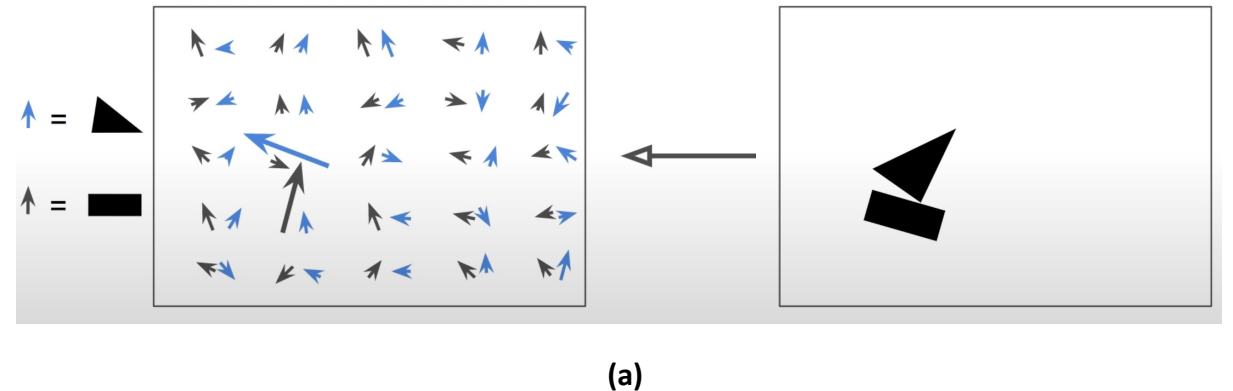
Spatio-temporal Features

- Capture how facial features **vary across frames**.
- **Temporal features** sensitive to variations over time.
- Contiguous frames in the **onset** and **offset** phases experience **high** variations.
- Spatio-temporal features provide more **descriptive** information during **onset** and **offset** phases.

Can we dynamically learn to selectively focus on spatial or spatio-temporal features?

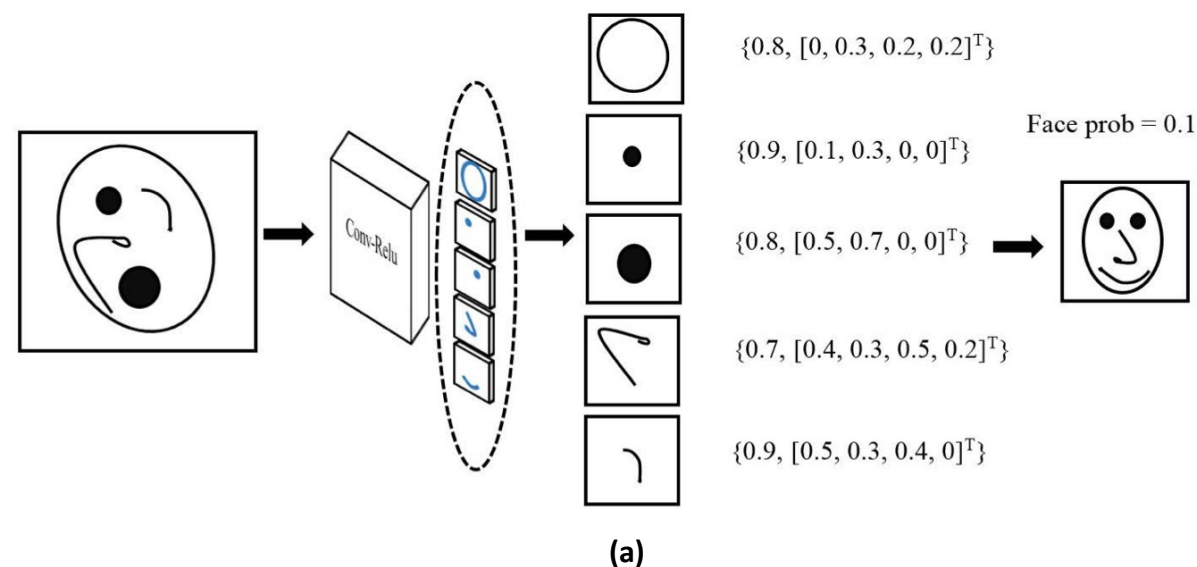
Motivation: Capsule Networks

- Capsules help encode **spatial primitives** or features constituting the object of interest.
- **Length** encodes **probability** of presence.
- **Orientation** encodes parameters such as **pose** variations.
- Local **spatial relationships learnt** between the object of interest and its surroundings.

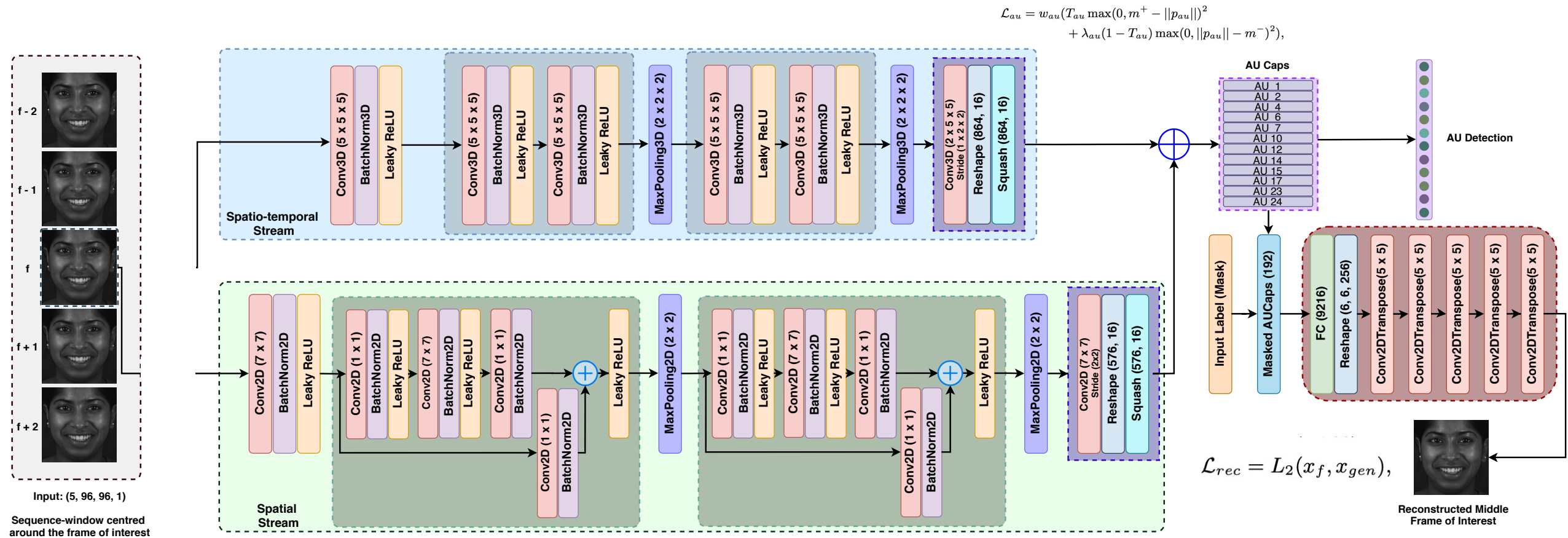


Motivation: Capsule Networks

- Each capsule may learn **features** relevant for **different parts** of the face.
- Capsules may **encode position, rotation, pose features** for each individual part.
- **Local relationships** between these features **guide model predictions**.
- Observing **contiguous frames** may help provide insights into how these relationships **vary with time**.



Action Unit Lifecycle-Aware Capsule Networks



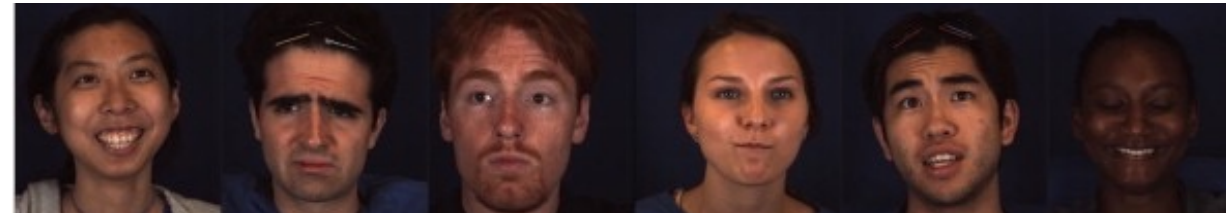
Evaluations

- Multi-label AU Prediction:
 - Evaluate model performance on **two datasets** for **12 Action Units**:

AU	Description	AU	Description	AU	Description
1	Inner Brow Raiser	7	Eyelid Tightener	15	Lip Corner Depressor
2	Outer Brow Raiser	10	Upper Lip Raiser	17	Chin Raiser
4	Brow Lowerer	12	Lip Corner Puller	23	Lip Tightener
6	Cheek Raiser	14	Dimpler	24	Lip Pressor

- Model Ablations:
 - Spatial vs. Spatio-temporal Features.
 - Convolutional vs. Capsule-based computations.
 - Window sizes.
- Model Visualisations:
 - Image Reconstructions.
 - Visualising Saliency Maps.

BP4D



(a)

GFT



(b)

AU Prediction: BP4D Dataset

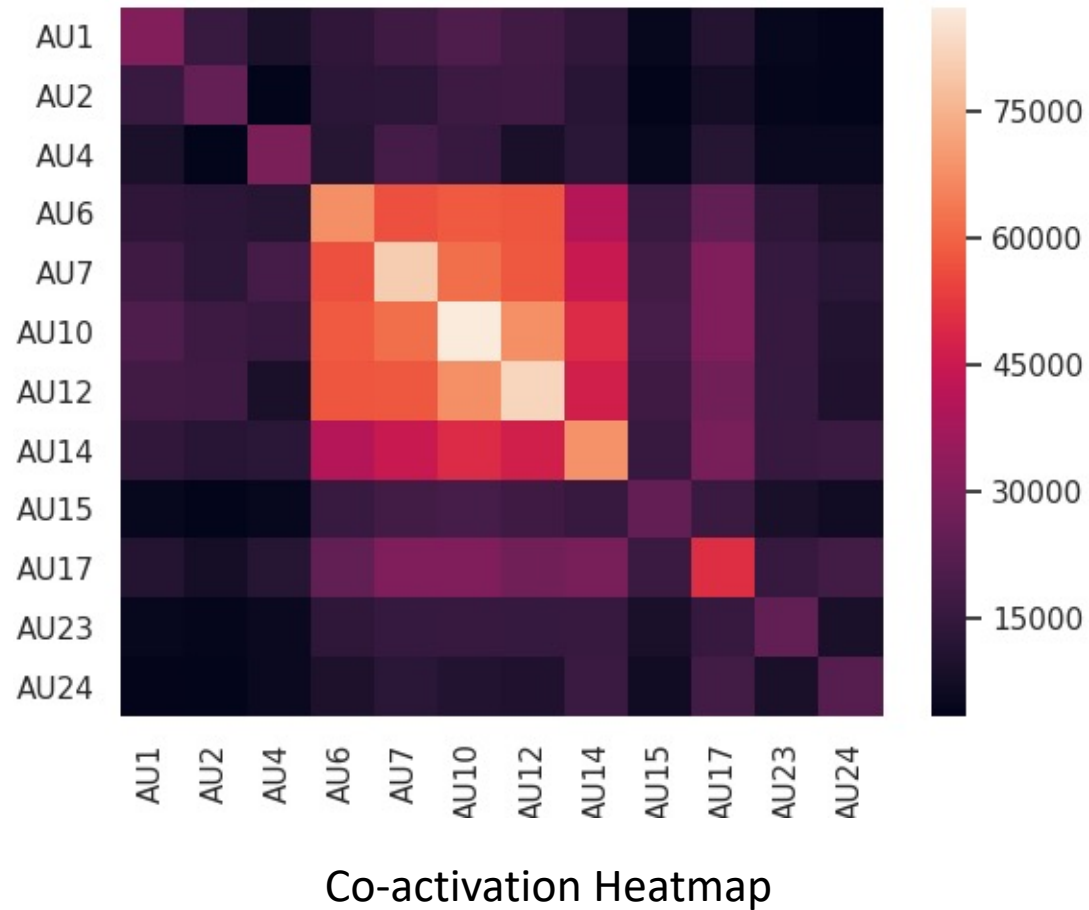


TABLE I: Performance Evaluation (F1-Scores) on BP4D. **Bold** values denote best while [*bracketed*] denote second-best values for each row.

AU	CNN-LSTM [6]	EAC [7]	ROI [33]	CapsNet [24]	J \hat{A} A [34]	SRERL [17]	STRAL [9]	AULA-Caps [Ours]
1	0.314	0.390	0.362	0.468	[0.538]	0.469	0.482	0.562
2	0.311	0.352	0.316	0.291	0.478	0.453	[0.477]	0.465
4	0.714	0.486	0.434	0.529	[0.582]	0.556	0.581	0.573
6	0.633	0.761	0.771	0.753	[0.785]	0.771	0.758	0.796
7	0.771	0.729	0.737	0.776	0.758	0.784	[0.781]	0.765
10	0.450	0.819	0.850	0.824	0.827	0.835	0.816	[0.843]
12	0.826	0.862	0.870	0.850	0.882	[0.876]	[0.876]	0.874
14	0.729	0.588	0.626	0.657	0.637	0.639	0.605	[0.718]
15	0.340	0.375	0.457	0.337	0.433	0.522	[0.502]	0.457
17	0.539	0.591	0.580	0.606	0.618	0.639	[0.640]	0.694
23	0.386	0.359	0.383	0.369	0.456	0.471	0.512	[0.495]
24	0.370	0.358	0.374	0.431	0.499	[0.533]	0.552	0.502
Avg.	0.532	0.559	0.564	0.574	0.624	0.629	[0.632]	0.645

AU Prediction: GFT Dataset

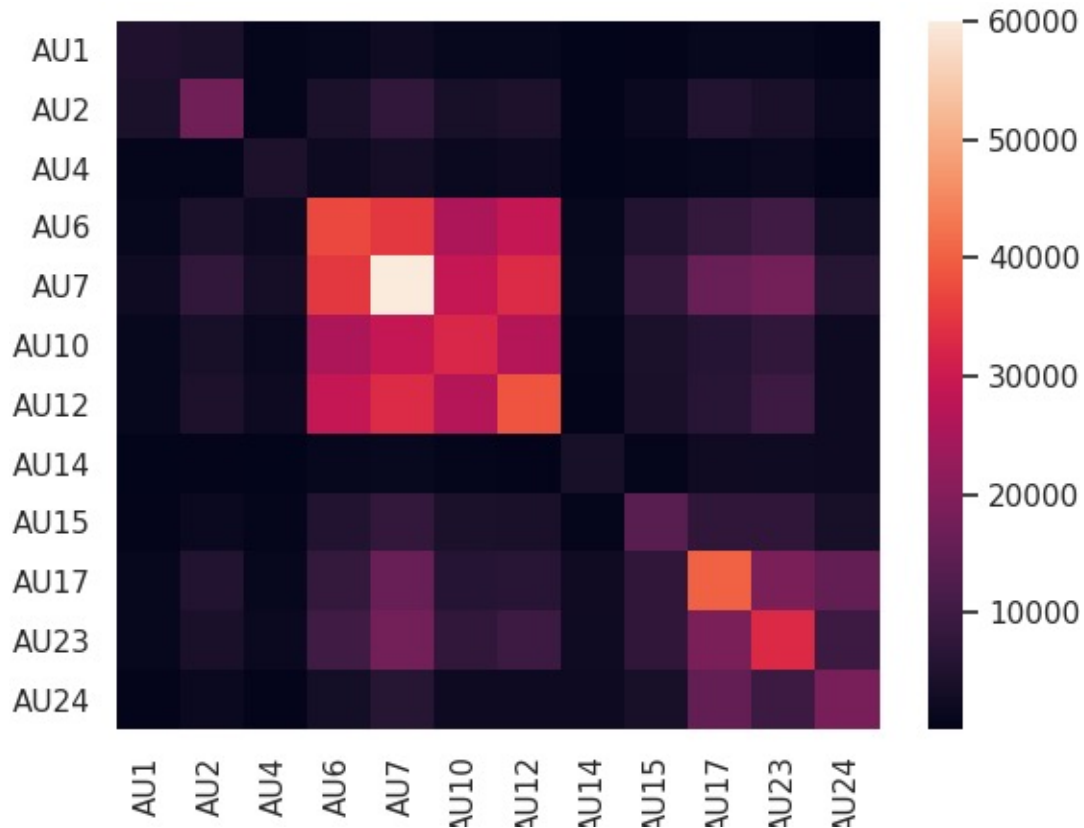


TABLE II: Performance Evaluation (F1-Scores) on GFT. **Bold** values denote best while [*bracketed*] denote second-best values for each row. *Averaged for 10 AUs.

AU	CRD [23]	ANet [6]	J \hat{A} A [34]	CNN-LSTM [6]	AULA-Caps [Ours]
1	[0.437]	0.312	0.465	0.299	[0.313]
2	0.449	0.292	[0.493]	0.257	0.498
4	0.198	0.719	0.192	[0.689]	[0.297]
6	0.746	0.645	0.790	0.673	[0.775]
7	0.721	0.671	–	[0.725]	0.772
10	0.765	0.426	[0.75]	0.670	0.749
12	[0.798]	0.731	0.848	0.751	0.785
14	0.500	[0.691]	0.441	0.807	[0.236]
15	0.339	0.279	0.335	0.435	[0.371]
17	0.170	[0.504]	–	0.491	0.592
23	0.168	0.348	0.549	0.350	[0.522]
24	0.129	0.390	[0.507]	0.319	0.530
Avg.	0.452	0.500	0.537*	0.539**	[0.537]

** Results on 50 out of 96 subjects.

Model Ablations

- Spatial vs. Spatio-Temporal Features:
 - 2D performs better than 3D on frame—based analyses.
 - Combining 2D and 3D features results in improved performance overall.
- Convolution vs. Capsule-based Computation:
 - Capsule-based computations provide improvements across evaluations.
 - # Parameters to be trained are decreased.
- Ablating Window Sizes:
 - Increasing Window size, on average improves performance.
 - Window size 5 (N=2) performs the best.

TABLE III: Ablations using BP4D dataset. Decoder parameters ($\approx 2.8\text{M}$) excluded for comparison with CNN baselines.

Model	Avg. F1-Score	#Params	RunTime / Batch
2D CNN Baseline	0.573	3.44M	0.31s
3D CNN Baseline	0.540	15.09M	0.63s
Dual-Stream CNN Baseline	0.596	25.6M	0.64s
2D Stream AULA-Caps	0.580	3.06M	0.35s
3D Stream AULA-Caps	0.550	8.46M	0.66s
AULA-Caps (N=1)	0.599	11.67M	0.71s
AULA-Caps (N=2)	0.645	11.51M	1.22s
AULA-Caps (N=3)	0.603	14.24M	1.66s
AULA-Caps (N=4)	0.619	14.32M	1.78s

Visualisations

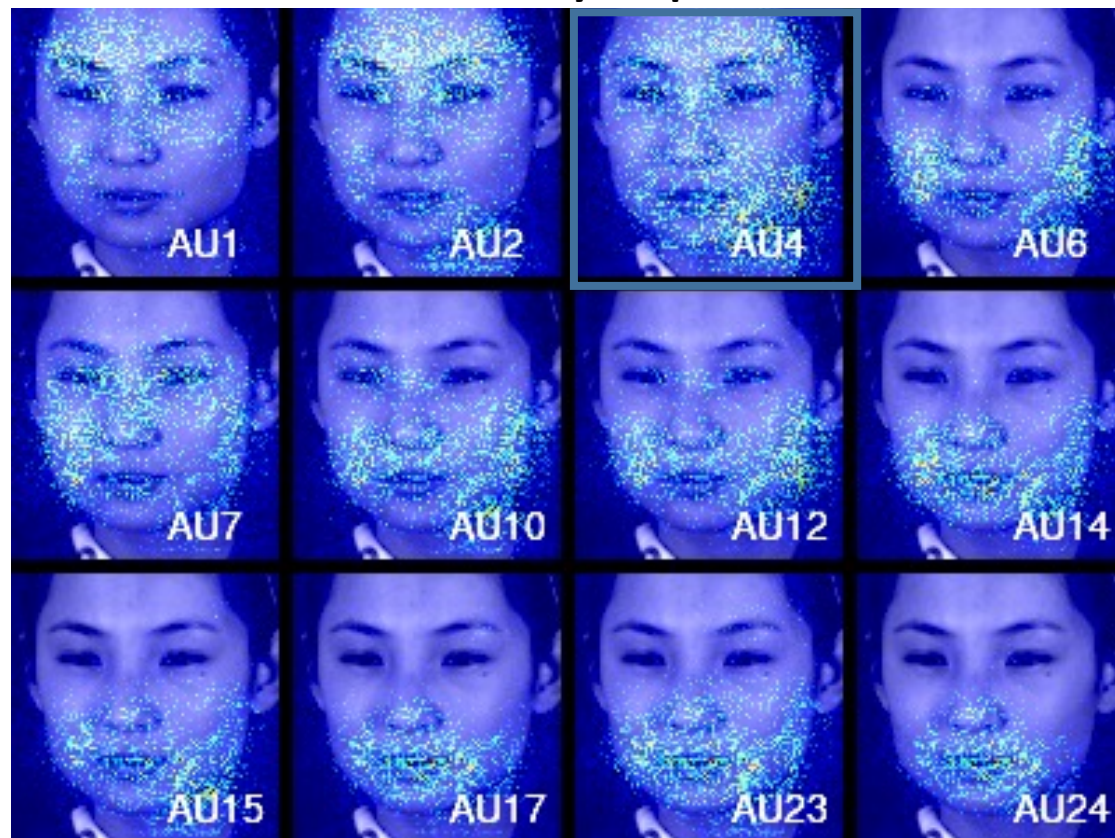
Input FoI Images



Reconstructed FoI Images



Saliency Maps



Take Away Message

Conclusions

- First implementation combining **spatial** and **spatio-temporal** capsule-based computations.
- Spatio-temporal information provides **context** for continuous AU prediction.
- Combining **spatial** and **spatio-temporal** feature primitives improves model performance.
- **Selectively focusing** on spatial and spatio-temporal features through capsule routing enables robustness.

Next Steps

- Model performance **sensitive** to sequence window length.
- Dynamically **adapting** window-size based on specific AU lifecycles using **anchor frames** (Lu *et al.* 2020).
- Data Imbalance major hurdle for multi-label classification problems.
 - Using co-activation patterns as context to improve model performance (Li *et al.* 2019).
 - Advanced methodologies such as Synthetic Instance Generation (Charte *et al.* 2015) or Continual Learning (Churamani *et al.* 2021).

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Hatice Gunes

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