Learning Socially Appropriate Robo-waiter Behaviours through Real-time User Feedback

Supplementary Data and Results

I. Data Collection

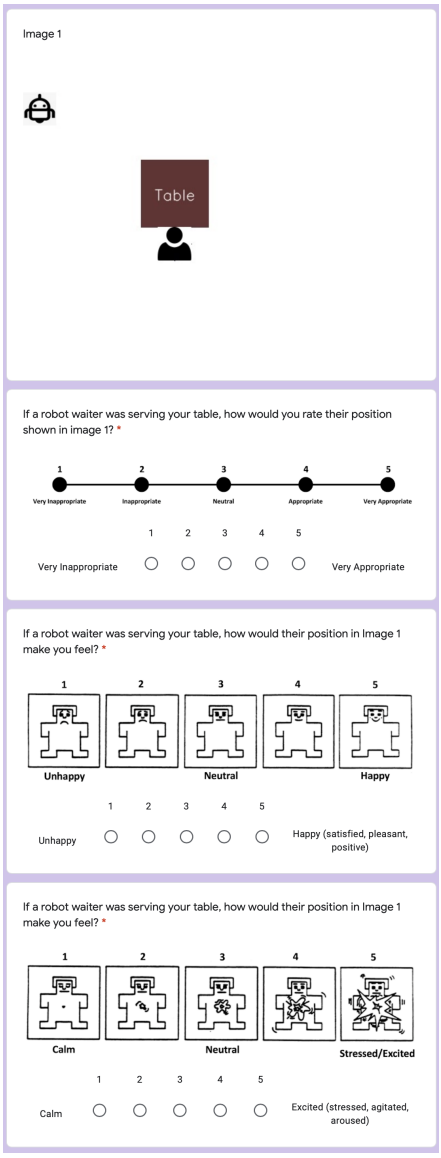

Fig. 1: An example of the questions asked to the participants in the online survey for data collection.

II. HRI User-study

A. *Implicit Feedback across Conditions*

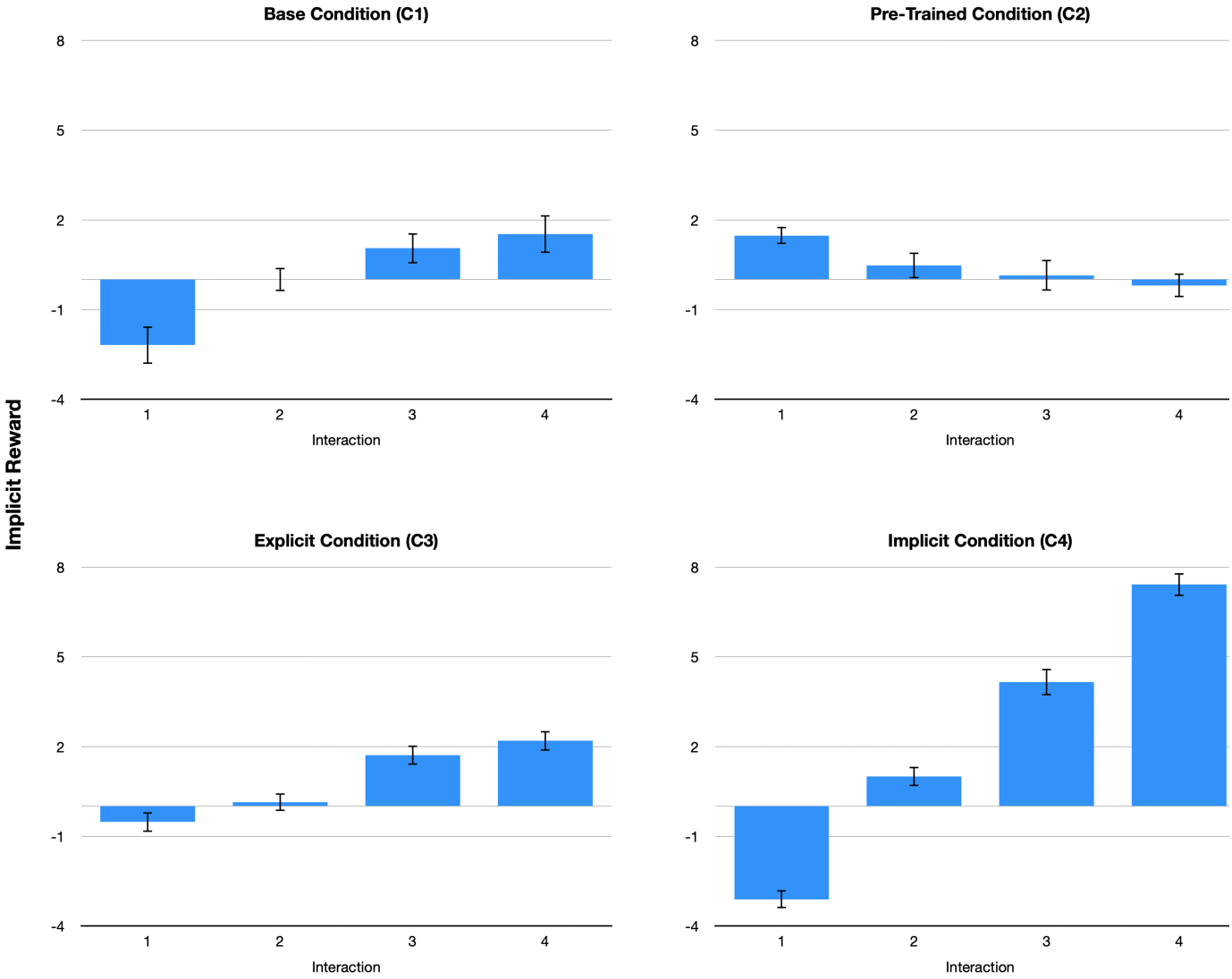

Fig. 2: Implicit feedback captured across the 4 tasks for each experiment condition. Implicit feedback is used to update the robot behaviour only in C4.

B. Explicit Feedback across Conditions

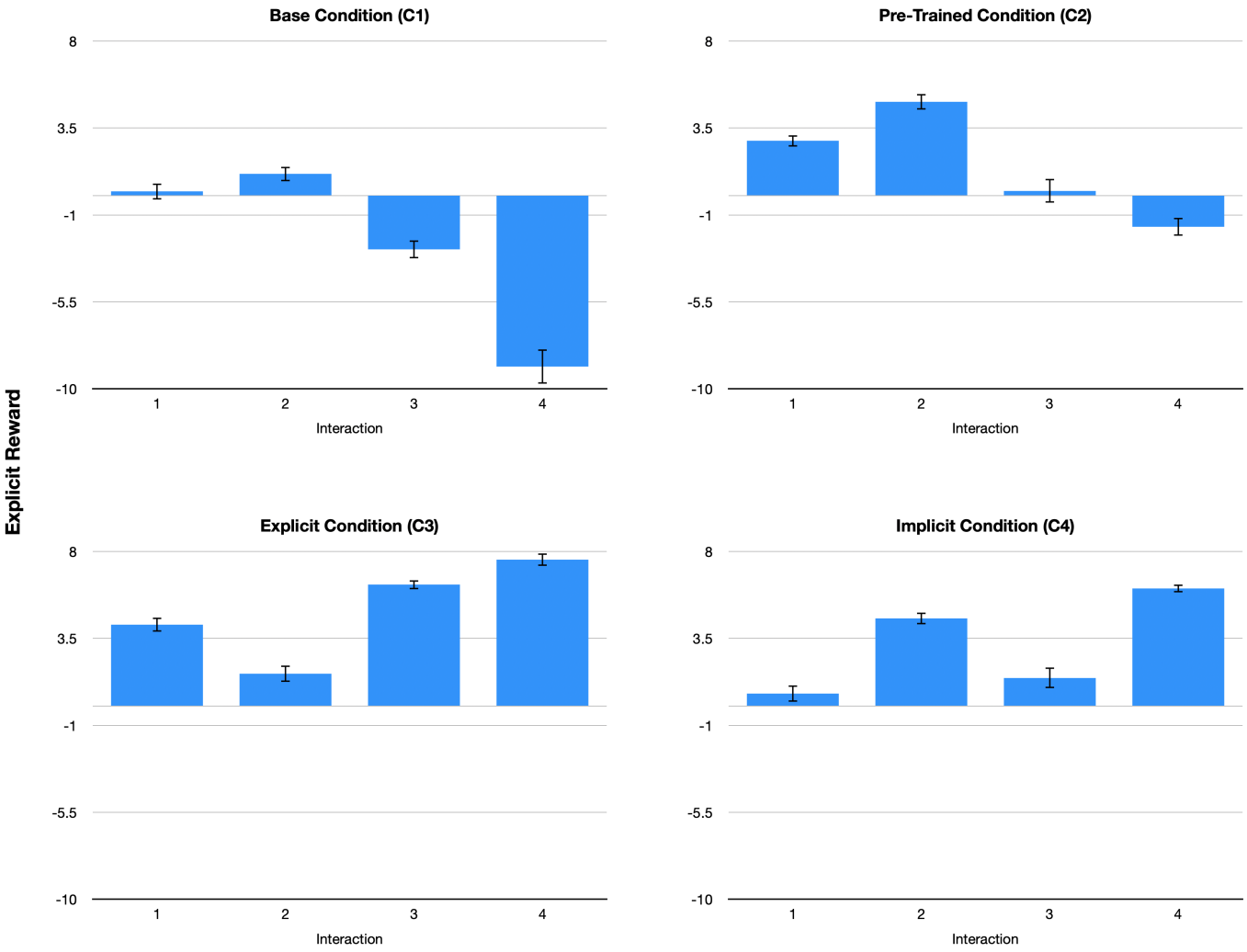

Fig. 3: Explicit feedback captured across the 4 tasks for each experiment condition. Explicit feedback is used to update the robot behaviour only in C3.